

NAG C Library Function Document

nag_zgetrs (f07asc)

1 Purpose

nag_zgetrs (f07asc) solves a complex system of linear equations with multiple right-hand sides, $AX = B$, $A^T X = B$ or $A^H X = B$, where A has been factorized by nag_zgetrf (f07arc).

2 Specification

```
void nag_zgetrs (Nag_OrderType order, Nag_TransType trans, Integer n, Integer nrhs,
                 const Complex a[], Integer pda, const Integer ipiv[], Complex b[],
                 Integer pdb, NagError *fail)
```

3 Description

To solve a complex system of linear equations $AX = B$, $A^T X = B$ or $A^H X = B$, this function must be preceded by a call to nag_zgetrf (f07arc) which computes the LU factorization of A as $A = PLU$. The solution is computed by forward and backward substitution.

If $\text{trans} = \text{Nag_NoTrans}$, the solution is computed by solving $PLY = B$ and then $UX = Y$.

If $\text{trans} = \text{Nag_Trans}$, the solution is computed by solving $U^T Y = B$ and then $L^T P^T X = Y$.

If $\text{trans} = \text{Nag_ConjTrans}$, the solution is computed by solving $U^H Y = B$ and then $L^H P^T X = Y$.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

1: **order** – Nag_OrderType *Input*

On entry: the **order** parameter specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this parameter.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **trans** – Nag_TransType *Input*

On entry: indicates the form of the equations as follows:

if **trans** = Nag_NoTrans, $AX = B$ is solved for X ;

if **trans** = Nag_Trans, $A^T X = B$ is solved for X ;

if **trans** = Nag_ConjTrans, $A^H X = B$ is solved for X .

Constraint: **trans** = Nag_NoTrans, Nag_Trans or Nag_ConjTrans.

3: **n** – Integer *Input*

On entry: n , the order of the matrix A .

Constraint: **n** ≥ 0 .

4:	nrhs – Integer	<i>Input</i>
<i>On entry:</i> r , the number of right-hand sides.		
<i>Constraint:</i> $\mathbf{nrhs} \geq 0$.		
5:	a [<i>dim</i>] – const Complex	<i>Input</i>
Note: the dimension, dim , of the array a must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.		
If order = Nag_ColMajor, the (i, j) th element of the matrix A is stored in a [($j - 1$) \times pda + $i - 1$] and if order = Nag_RowMajor, the (i, j) th element of the matrix A is stored in a [($i - 1$) \times pda + $j - 1$].		
<i>On entry:</i> the LU factorization of A , as returned by nag_zgetrf (f07arc).		
6:	pda – Integer	<i>Input</i>
<i>On entry:</i> the stride separating matrix row or column elements (depending on the value of order) in the array a .		
<i>Constraint:</i> $\mathbf{pda} \geq \max(1, \mathbf{n})$.		
7:	ipiv [<i>dim</i>] – const Integer	<i>Input</i>
Note: the dimension, dim , of the array ipiv must be at least $\max(1, \mathbf{n})$.		
<i>On entry:</i> the pivot indices, as returned by nag_zgetrf (f07arc).		
8:	b [<i>dim</i>] – Complex	<i>Input/Output</i>
Note: the dimension, dim , of the array b must be at least $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when order = Nag_ColMajor and at least $\max(1, \mathbf{pdb} \times \mathbf{n})$ when order = Nag_RowMajor.		
If order = Nag_ColMajor, the (i, j) th element of the matrix B is stored in b [($j - 1$) \times pdb + $i - 1$] and if order = Nag_RowMajor, the (i, j) th element of the matrix B is stored in b [($i - 1$) \times pdb + $j - 1$].		
<i>On entry:</i> the n by r right-hand side matrix B .		
<i>On exit:</i> the n by r solution matrix X .		
9:	pdb – Integer	<i>Input</i>
<i>On entry:</i> the stride separating matrix row or column elements (depending on the value of order) in the array b .		
<i>Constraints:</i>		
if order = Nag_ColMajor, $\mathbf{pdb} \geq \max(1, \mathbf{n})$; if order = Nag_RowMajor, $\mathbf{pdb} \geq \max(1, \mathbf{nrhs})$.		
10:	fail – NagError *	<i>Output</i>
The NAG error parameter (see the Essential Introduction).		

6 Error Indicators and Warnings

NE_INT

On entry, **n** = $\langle value \rangle$.

Constraint: $\mathbf{n} \geq 0$.

On entry, **nrhs** = $\langle value \rangle$.

Constraint: $\mathbf{nrhs} \geq 0$.

On entry, **pda** = $\langle value \rangle$.

Constraint: $\mathbf{pda} > 0$.

On entry, **pdb** = $\langle value \rangle$.

Constraint: $\mathbf{pdb} > 0$.

NE_INT_2

On entry, **pda** = $\langle value \rangle$, **n** = $\langle value \rangle$.
 Constraint: **pda** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$, **n** = $\langle value \rangle$.
 Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$, **nrhs** = $\langle value \rangle$.
 Constraint: **pdb** $\geq \max(1, \mathbf{nrhs})$.

NE_ALLOC_FAIL

Memory allocation failed.

NE_BAD_PARAM

On entry, parameter $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy

For each right-hand side vector b , the computed solution x is the exact solution of a perturbed system of equations $(A + E)x = b$, where

$$|E| \leq c(n)\epsilon P|L||U|,$$

$c(n)$ is a modest linear function of n , and ϵ is the **machine precision**.

If \hat{x} is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_\infty}{\|x\|_\infty} \leq c(n) \operatorname{cond}(A, x)\epsilon$$

where $\operatorname{cond}(A, x) = \| |A^{-1}| |A| |x| \|_\infty / \|x\|_\infty \leq \operatorname{cond}(A) = \| |A^{-1}| |A| \|_\infty \leq \kappa_\infty(A)$. Note that $\operatorname{cond}(A, x)$ can be much smaller than $\operatorname{cond}(A)$, and $\operatorname{cond}(A^H)$ (which is the same as $\operatorname{cond}(A^T)$) can be much larger (or smaller) than $\operatorname{cond}(A)$.

Forward and backward error bounds can be computed by calling nag_zgerfs (f07avc), and an estimate for $\kappa_\infty(A)$ can be obtained by calling nag_zgecon (f07auc) with **norm** = Nag_InfNorm.

8 Further Comments

The total number of real floating-point operations is approximately $8n^2r$.

This function may be followed by a call to nag_zgerfs (f07avc) to refine the solution and return an error estimate.

The real analogue of this function is nag_dgetrs (f07aec).

9 Example

To solve the system of equations $AX = B$, where

$$A = \begin{pmatrix} -1.34 + 2.55i & 0.28 + 3.17i & -6.39 - 2.20i & 0.72 - 0.92i \\ -0.17 - 1.41i & 3.31 - 0.15i & -0.15 + 1.34i & 1.29 + 1.38i \\ -3.29 - 2.39i & -1.91 + 4.42i & -0.14 - 1.35i & 1.72 + 1.35i \\ 2.41 + 0.39i & -0.56 + 1.47i & -0.83 - 0.69i & -1.96 + 0.67i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 26.26 + 51.78i & 31.32 - 6.70i \\ 6.43 - 8.68i & 15.86 - 1.42i \\ -5.75 + 25.31i & -2.15 + 30.19i \\ 1.16 + 2.57i & -2.56 + 7.55i \end{pmatrix}.$$

Here A is nonsymmetric and must first be factorized by nag_zgetrf (f07arc).

9.1 Program Text

```
/* nag_zgetrs (f07asc) Example Program.
*
* Copyright 2001 Numerical Algorithms Group.
*
* Mark 7, 2001.
*/
#include <stdio.h>
#include <nag.h>
#include <nag_stdl�.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer i, ipiv_len, j, n, nrhs, pda, pdb;
    Integer exit_status=0;
    NagError fail;
    Nag_OrderType order;
    /* Arrays */
    Complex *a=0, *b=0;
    Integer *ipiv=0;

#ifdef NAG_COLUMN_MAJOR
#define A(I,J) a[(J-1)*pda + I - 1]
#define B(I,J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I,J) a[(I-1)*pda + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);
    Vprintf("f07asc Example Program Results\n\n");
    /* Skip heading in data file */
    Vscanf("%*[^\n] ");
    Vscanf("%ld%ld%*[^\n] ", &n, &nrhs);
#ifdef NAG_COLUMN_MAJOR
    pda = n;
    pdb = n;
#else
    pda = n;
    pdb = nrhs;
#endif
    ipiv_len = n;

    /* Allocate memory */
    if ( !(a = NAG_ALLOC(n * n, Complex)) ||
        !(b = NAG_ALLOC(n * nrhs, Complex)) ||
        !(ipiv = NAG_ALLOC(ipiv_len, Integer)) )
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read A and B from data file */

```

```

for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= n; ++j)
    {
        Vscanf(" ( %lf , %lf )", &A(i,j).re, &A(i,j).im);

    }
}
Vscanf("%*[^\n] ");
for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= nrhs; ++j)
        Vscanf(" ( %lf , %lf )", &B(i,j).re, &B(i,j).im);
}
Vscanf("%*[^\n] ");

/* Factorize A */
f07arc(order, n, n, a, pda, ipiv, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07arc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Compute solution */
f07asc(order, Nag_NoTrans, n, nrhs, a, pda, ipiv, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from f07asc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print solution */
x04dbc(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs, b, pdb,
        Nag_BracketForm, "%7.4f", "Solution(s)", Nag_IntegerLabels, 0,
        Nag_IntegerLabels, 0, 80, 0, 0, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from x04dbc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
if (a) NAG_FREE(a);
if (b) NAG_FREE(b);
if (ipiv) NAG_FREE(ipiv);
return exit_status;
}

```

9.2 Program Data

```

f07asc Example Program Data
 4 2 :Values of N and NRHS
(-1.34, 2.55) ( 0.28, 3.17) (-6.39,-2.20) ( 0.72,-0.92)
(-0.17,-1.41) ( 3.31,-0.15) (-0.15, 1.34) ( 1.29, 1.38)
(-3.29,-2.39) (-1.91, 4.42) (-0.14,-1.35) ( 1.72, 1.35)
( 2.41, 0.39) (-0.56, 1.47) (-0.83,-0.69) (-1.96, 0.67) :End of matrix A
(26.26, 51.78) (31.32, -6.70)
( 6.43, -8.68) (15.86, -1.42)
(-5.75, 25.31) (-2.15, 30.19)
( 1.16, 2.57) (-2.56, 7.55) :End of matrix B

```

9.3 Program Results

f07asc Example Program Results

Solution(s)

	1	2
1	(1.0000, 1.0000)	(-1.0000, -2.0000)
2	(2.0000, -3.0000)	(5.0000, 1.0000)
3	(-4.0000, -5.0000)	(-3.0000, 4.0000)
4	(0.0000, 6.0000)	(2.0000, -3.0000)
